



Gurobi Connect Chicago

Advanced Modeling

Rodrigo Fuentes
Sr. Technical Account Manager





Agenda

Gurobi Python Extensions

Advanced Modeling Features

- Range constraints
- Non-linear functions
- Special Ordered Sets
- General constraints
- Logical conditions
- Semi-continuous variables
- Selecting Big-M values

Multiple Objectives

Gurobi Python Extensions



python™

- Python provides data structures that are well-suited for deploying optimization models:
 - Tuples
 - Lists
 - Sets
 - Dictionaries
- On top of that, gurobipy also offers a few data structures that allow you to build subsets from a collection of tuples efficiently:
 - Tuplelists
 - Tupledicts
 - Multidicts

Tuple

A tuple is an ordered, compound grouping that cannot be modified once it is created. It is ideal for representing multi-dimensional subscripts.

```
mytuple = ('truck22', 'truck37') # create
print(mytuple[0]) # access
```

List

A list is an ordered group, so each item is indexed. Lists can be modified by adding, deleting or sorting elements.

```
mylist = ['truck22', 'truck37', 'truck53'] # create
print(mylist[1]) # access
```

Set

A set is an unordered group. As such, sets can only be modified by adding or deleting elements. Unlike lists, sets cannot have repeated elements.

```
myset = {'truck22', 'truck37', 'truck53'}
for item in myset:
    print(item)
```

Dictionary

A dictionary is a mapping from keys to values that is ideal for representing indexed data, e.g. cost, demand, capacity, etc. Typically strings, numbers, and tuples are used as keys, which should be unique.

```
demand = {
    'demand4': 20,
    'demand22': 40,
}
print(demand['demand22'])
```

Tuplelist

This is Gurobi's extension of a Python list to efficiently build sub-lists from a list of tuples.

```
mytuplelist = gp.tuplelist([
    ("demand4", "truck22"), ("demand4", "truck37"), ("demand4", "truck53"),
    ("demand22", "truck22"),])
print(mytuplelist[2]) # = ('demand4', 'truck53') (tuple)
print(mytuplelist.select("demand4", "*")) # Prints all tuples with 'demand4'
```

Tupledict

This is Gurobi's extension of a Python dictionary for creating subsets of Gurobi variable objects. The keys of a tupledict are stored as a tuplelist, which enables the efficient creation of math expressions that contain a subset of matching variables by using methods like tupledict.select(), tupledict.sum() or tupledict.prod().

```
assign = model.addVars(expertise, name="assign") # returns a tupledict
supply = model.addConstrs((assign.sum(r, "*") == 1 for r in resources))
```

Multidict

As its name implies, multidict is a convenience function to define multiple dictionaries (each one with the same set of keys) and their indices in one statement. Specifically, the input consists of a Python dictionary with lists of the same length as the values associated with the keys. The first output of this function is a tuplelist, and the rest are tupledicts.

```
building_truck_spot_pairs, distance, scaled_demand = gp.multidict({
    ('demand4', 'truck11'): [112.7, 20],
    ('demand4', 'truck10'): [149.3, 15],
    ('demand22', 'truck11'): [155.7, 10]
})
print(scaled_demand.sum('*', 'truck11')) # = 30
```


`building_truck_spot_pairs = [('demand4', 'truck11'), ('demand4', 'truck10'), ('demand22', 'truck11')]`
multidict

tuplelist of keys to

`distance = {('demand4', 'truck11'): 112.7,
 ('demand4', 'truck10'): 149.3,
 ('demand22', 'truck11'): 155.7 }`

#tupledict

`scaled_demand = {('demand4', 'truck11'): 20,
 ('demand4', 'truck10'): 15,
 ('demand22', 'truck11'): 10 }`

A red callout bubble with a tail pointing towards the "#tupledict" label. It contains the text "1 dimensional item here, but could be tuple of arbitrary dimension".

1 dimensional
item here, but
could be tuple of
arbitrary
dimension

A Gurobi class to store lists of tuples

```
>>> import gurobipy as gp
>>> from gurobipy import GRB
Cities = ['A', 'B', 'C', 'D']
Routes = gp.tuplelist([('A', 'B'), ('A', 'C'), ('B', 'C'), ('B', 'D'), ('C', 'D')])
```

What makes it special: select() statement for efficient filtering

```
for c in Cities:
    print(Routes.select(c, '*'))
# [('A', 'B'), ('A', 'C')]
# [('B', 'C'), ('B', 'D')]
# [('C', 'D')]
# [] No routes with D as origin
```

The *tuplelist* is indexed to make select() efficient

Each select() call returns a tuplelist

Using integers

```
x = model.addVars(2, 3, name="x")  
# x[0,0], x[0,1], x[0,2], x[1,0], x[1,1], x[1,2]
```

	0	1	2
0	(0,0)	(0,1)	(0,2)
1	(1,0)	(1,1)	(1,2)

(variable names)

Using lists of scalars

```
y = model.addVars(Cities, Cities, name="y")  
# y[A,A], y[A,B], y[A,C], y[A,D], y[B,A], y[B,B], y[B,C], y[B,D]  
# y[C,A], y[C,B], y[C,C], y[C,D], y[D,A], y[D,B], y[D,C], y[D,D]
```

Using a tuplelist

```
z = model.addVars(Routes, name="z") # z[A,B], z[A,C], z[B,C], z[B,D], z[C,D]
```

Using a generator expression

```
w = model.addVars((i for i in range(5) if i != 2), name="w")  
# w[0], w[1], w[3], w[4]  
# w = 0: <gurobi.Var w[0]>, 1: <gurobi.Var w[1]>, 3: <gurobi.Var w[3]>, 4: <gurobi.Var w[4]>  
# tupledict with indices as keys and variables as value
```

Automatically takes the cross-product of multiple indices

```
x = model.addVars(2, 3, name="x")  
y = model.addVars(Cities, Cities, name="y")
```

addVars call with vs without provided "name", generates names automatically, using the indices:

name="x":

```
{(0, 0): <gurobi.Var x[0,0]>,  
 (0, 1): <gurobi.Var x[0,1]>,  
 (0, 2): <gurobi.Var x[0,2]>,  
 (1, 0): <gurobi.Var x[1,0]>,  
 (1, 1): <gurobi.Var x[1,1]>,  
 (1, 2): <gurobi.Var x[1,2]>}
```

no name specified:

```
{(0, 0): <gurobi.Var C0>,  
 (0, 1): <gurobi.Var C1>,  
 (0, 2): <gurobi.Var C2>,  
 (1, 0): <gurobi.Var C3>,  
 (1, 1): <gurobi.Var C4>,  
 (1, 2): <gurobi.Var C5>}
```

Recall

```
Routes = tuplelist([('A','B'), ('A','C'), ('B','C'), ('B','D'), ('C','D')])
```

Can use a generator expression to build constraints

```
x = model.addVars(Routes, name="x")
y = model.addVars(Routes, name="y")
model.addConstrs((x[i,j]+y[i,j] <= 2 for i,j in Routes), name="capacity")
```

```
{('A', 'B'): <gurobi.Constr capacity[A,B]>,
 ('A', 'C'): <gurobi.Constr capacity[A,C]>,
 ('B', 'C'): <gurobi.Constr capacity[B,C]>,
 ('B', 'D'): <gurobi.Constr capacity[B,D]>,
 ('C', 'D'): <gurobi.Constr capacity[C,D]>}
```

Summary: variable and constraint indices are keys in a tupledict, with the actual constraints and variables being the associated values

Linear and quadratic expressions are used in constraints and the objective

- Basic (binary) mathematical operators ($+$ $-$ \times \div)
- Aggregate sum operator (\sum)
Used alone as well as in products (dot product)

Aggregate sum: using `tupledict.sum()`

A `tupledict` of variables has a `sum()` function, using the same syntax as `tuplelist.select()`:

```
x = model.addVars(3, 4, vtype=GRB.BINARY, name="x")
model.addConstrs(x.sum(i, '*') <= 1 for i in range(3))
```

This generates the constraints:

```
x[0,0] + x[0,1] + x[0,2] + x[0,3] <= 1
x[1,0] + x[1,1] + x[1,2] + x[1,3] <= 1
x[2,0] + x[2,1] + x[2,2] + x[2,3] <= 1
```

Aggregate sum: using quicksum()

Use generator expression inside a `quicksum()` function

```
obj = quicksum(cost[i,j] * x[i,j] for i,j in Routes)
```

Note:

`quicksum()` works just like Python's `sum()` function, but it is more efficient for optimization models.

A `tupledict` of variables has a `prod()` function to compute the dot product.

If `cost` is a dictionary, then the following are equivalent:

```
obj = quicksum(cost[i,j] * x[i,j] for i,j in arcs)
```

```
obj = x.prod(cost)
```

Another example:

```
x = m.addVars([(1,2), (1,3), (2,3)])
```

```
coeff = dict([(1,2), 2.0], [(1,3), 2.1], [(2,3), 3.3])
```

```
expr = x.prod(coeff) # LinExpr: 2.0 x[1,2] + 2.1 x[1,3] + 3.3 x[2,3]
```

```
expr = x.prod(coeff, '*', 3) # LinExpr: 2.1 x[1,3] + 3.3 x[2,3]
```

Takes the keys in `coeff`, multiplies the associated values by the values in `x` corresponding to the same keys.

Support NumPy's ndarrays and scipy.sparse matrices as input

- More convenient if the underlying model is naturally expressed with matrices
- Faster because no modeling objects for individual linear expressions are created

Add matrix variables

```
x = model.addMVar(shape)
```

Add matrix constraints

```
model.addMConstr(A, x, sense, b)
```

Add regular constraints with overload operator

```
model.addConstr(A @ x <= b)
```

Set a quadratic objective function

```
model.setObjective(x @ Q @ x)
```


Advanced Modeling Features



Background

Range constraints

Many models contain constraints like:

$$L \leq \sum_i a_i x_i \leq U$$

These can be rewritten as:

$$\begin{aligned} r + \sum_i a_i x_i &= U \\ 0 \leq r &\leq U - L \end{aligned}$$

The range constraint interface automates this for you

- `model.addRange($\sum_i a_i x_i$, L , U , "range0")`

If you need to modify the range

- Retrieve the additional range variable, named `RgYourConstraintName`
- Modify the bounds on that variable

For full control, it may be easier to model this yourself.

- Useful for efficient deactivation/reactivation of constraints in the model
 - Set infinite bounds on r to deactivate

General Constraints for popular logical expressions

- Absolute value
- Min/Max value
- And/Or over binary variables
- Indicator (if-then logic)

The General Constraint syntax is a safe way to implement model logic.

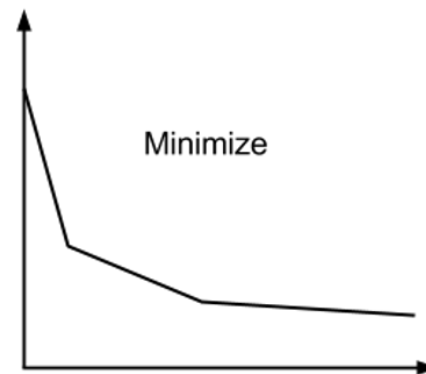
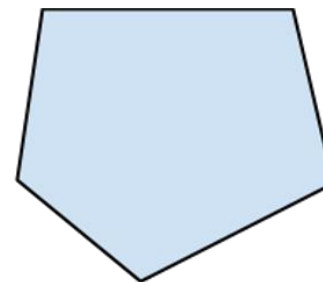
Coming Up:

- How do these logical expressions work?
- How to build models with complex logic?

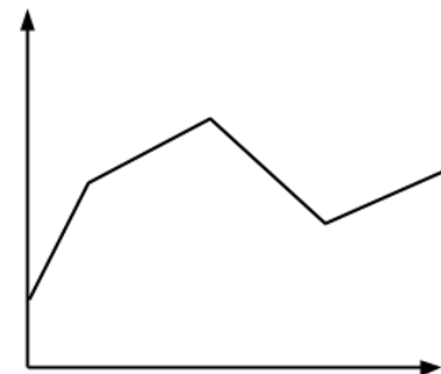
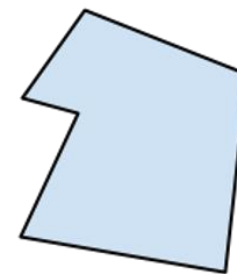
Background

Convexity (or not)

Models with convex regions and convex functions are generally much easier to solve



Convex



Non-convex

Background

Special Ordered Sets

Special Ordered Set of type 1 – at most one variable may be $\neq 0$ in a solution:

$$\text{SOS1 } (x_1, \dots, x_n)$$

Special Ordered Set of type 2 – an ordered set where

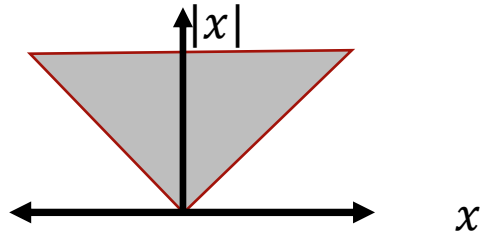
- At most two variables may be $\neq 0$ in a solution
- Non-zero variables must be adjacent

$$\text{SOS2 } (x_1, \dots, x_n)$$

Variables do not need to be integer.

Absolute value – Convex case

Simply substitute if absolute value function creates a convex model



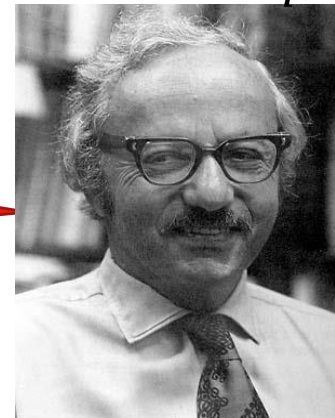
$\min |x|$
<linear constraints, some with x >
 x free



$\min z$
 $z = x_p + x_n$
 $x = x_p - x_n$
<lin constraints, some with
 x >
 x free, $z, x_p, x_n \geq 0$

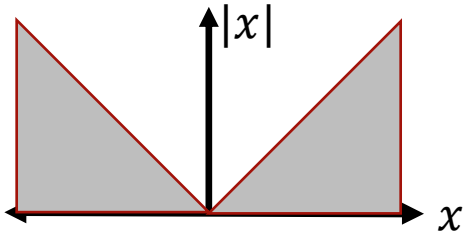
What about
 $x_p = 6, x_n$
 $= 4, x = 2, z$
 $= 10$?

Dual argument: solution is
feasible but not optimal,
any optimal solution has
either x_p or $x_n = 0$

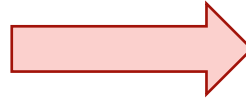


Primal
argument: 4
variables
away from
their
bounds, but
only room
for three
basic
variables

Use indicator variable and arbitrary big-M value to prevent both x_p and x_n positive



$\max |x|$
<linear constraints, some with x >
 x free



$\max z$

$$z = x_p + x_n$$

$$x = x_p - x_n = (x_p + \Delta) - (x_n + \Delta)$$

<linear constraints, some with x >

$$x_p \leq My$$

$$x_n \leq M(1 - y)$$

$$y \in \{0,1\},$$

$$x \text{ free}, z, x_p, x_n \geq 0$$

Can't rely on dual argument to force x_p or x_n to 0

Need some logic instead

Q: Any ideas on how to model this if no reasonable, finite big-M exists (ex: $|x|$ can be infinite)?

Use SOS-1 constraint to prevent both x_p and x_n positive

$\max |x|$
<constraints, some with x >
 x free



$\max z$
 $z = x_p + x_n$
 $x = x_p - x_n$
 $x_p, x_n \in \text{SOS1}$
<constraints, some with x >
 x free, $z, x_p, x_n \geq 0$

- No big-M value needed
- Works for both convex and non-convex version
 - No branching needed in the convex case

Q: Which formulation performs better?

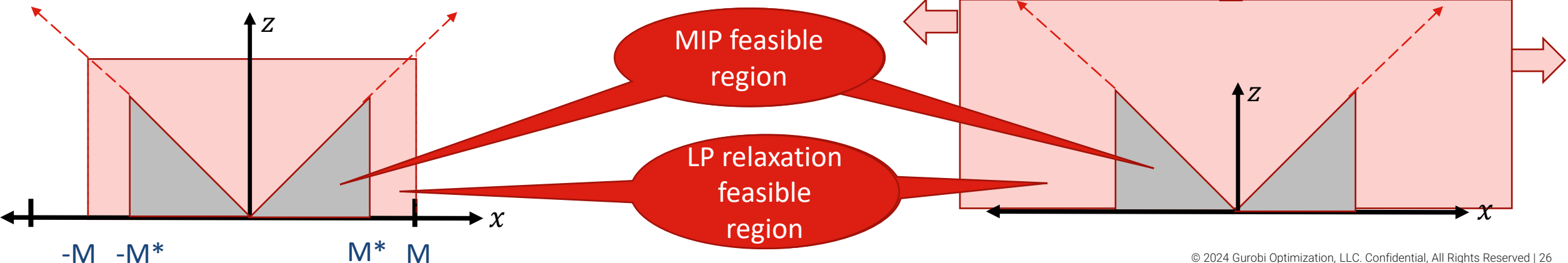
Which LP relaxation is stronger?

$$\begin{aligned} \max z \\ z &= x_p + x_n \\ x &= x_p - x_n \\ x_p &\leq My \\ x_n &\leq M(1 - y) \\ \text{<constraints, some with } x\text{>} \\ x \text{ free, } y &\in \{0,1\}, z, x_p, x_n \geq 0 \end{aligned}$$

Binary variables are better if modest M is known (or can be derived from model).

$$\begin{aligned} \max z \\ z &= x_p + x_n \\ x &= x_p - x_n \\ x_p, x_n &\in \text{SOS-1} \\ \text{<constraints, some with } x\text{>} \\ x \text{ free, } z, x_p, x_n &\geq 0 \end{aligned}$$

SOS is better, avoiding bad numerics, if M has to be arbitrarily large.



| SOS constraints vs big-M representation

SOS constraints are handled with branching rules (not included in LP relaxation)

Gurobi will try to reformulate SOS constraints into a big-M representation during presolve

- Gurobi's presolve has very powerful bound strengthening features that can reduce the largest big-M
- User has control over this behavior with `PreSOS1BigM` and `PreSOS2BigM` parameters
- This sets a limit on the largest big-M necessary

SOS advantages

- Always valid (no reasonable M in some cases)
- Numerically stable; no large M values

Big-M advantages:

- LP relaxation is tighter
- Typically results in better performance for Gurobi's algorithms as long as M is relatively small
- LP relaxation weakens as M increases
- Formulations are equivalent if M is infinite

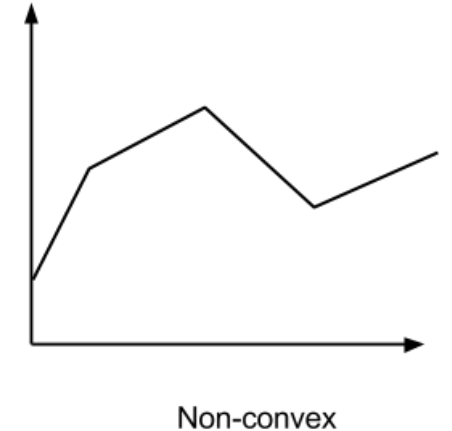
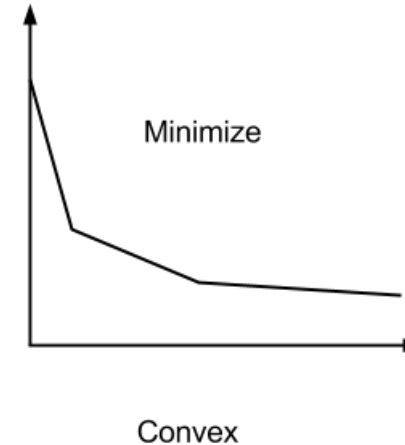
Generalization of absolute value functions

Convex case is “easy”

- Function represented by LP

Non-convex case is more challenging

- Function represented as MIP or SOS-2 constraints



Gurobi has an API for piecewise linear objectives (and constraints with 9.0)

- Built-in algorithmic support for the convex case (objective)
- Conversion to MIP is transparent to the user

Q: What are some potential applications?

Piecewise linear functions appear in models all the time

- Fixed costs in manufacturing due to setup
- Economies of scale when discounts are applied after buying a certain number of items
- ...

Also useful when approximating non-linear functions

- More pieces provide for a better approximation
- Trade-off between performance and exactness

Examples:

- Unit commitment models in energy sector
- Pooling problem
- Trigonometric, logarithmic and other nonlinear univariate functions

Gurobi versions ≥ 9.0 can handle the nonconvex quadratic pooling constraints explicitly

Gurobi versions ≥ 11.0 can handle selected univariate nonlinear functions explicitly

Only need to specify function breakpoints

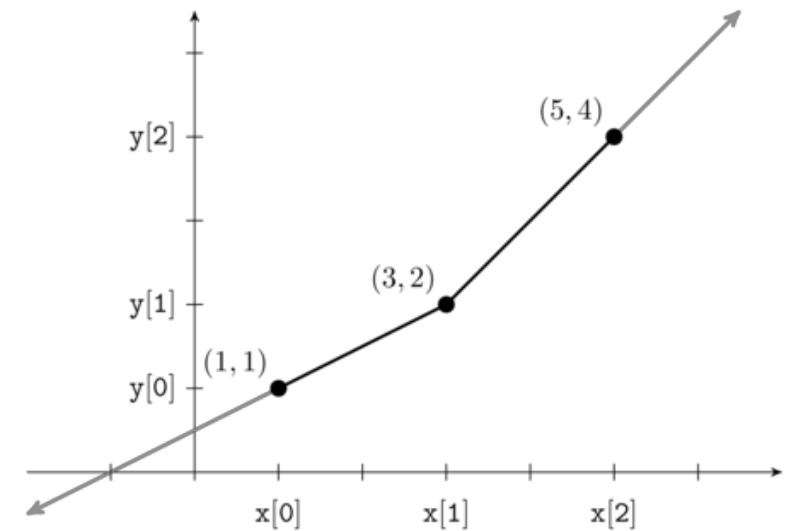
- No auxiliary variables or constraints necessary

Python example:

```
model.setPWLObj(x, [1, 3, 5], [1, 2, 4])  
model.addGenConstrPWL(x, y, xpts, ypts, "gc")
```

x must be non-decreasing

- Repeat x value for a jump (or discontinuity)



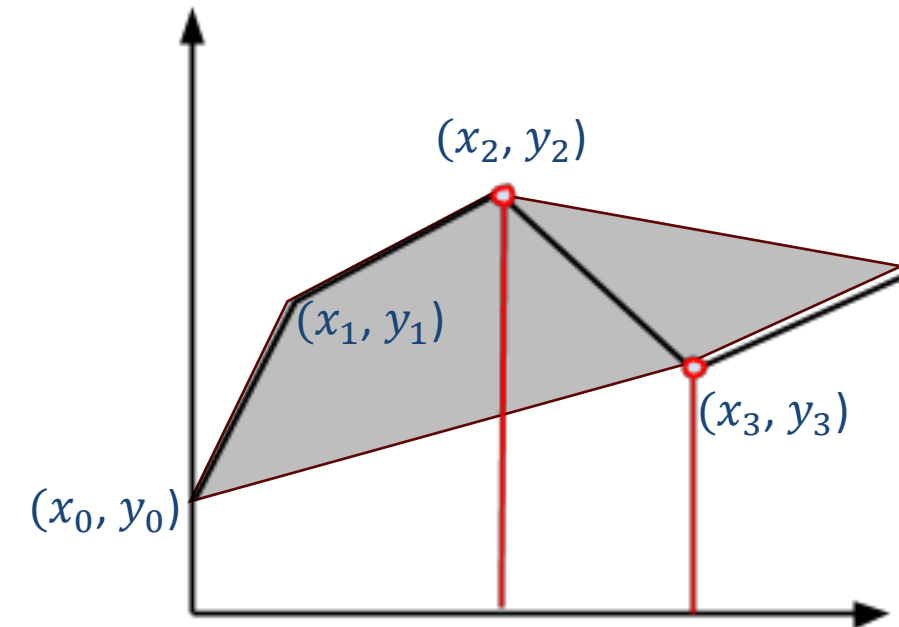
Piecewise linear functions – SOS-2 constraint

Let (x_i, y_i) represent i^{th} point in piecewise linear function

To represent $y = f(x)$, use:

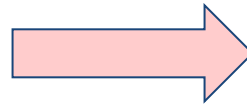
$$\begin{aligned}x &= \sum_i \lambda_i x_i \\y &= \sum_i \lambda_i y_i \\ \sum_i \lambda_i &= 1 \\ \lambda_i &\geq 0, \text{ SOS2}\end{aligned}$$

SOS-2 constraint is redundant if f is convex.

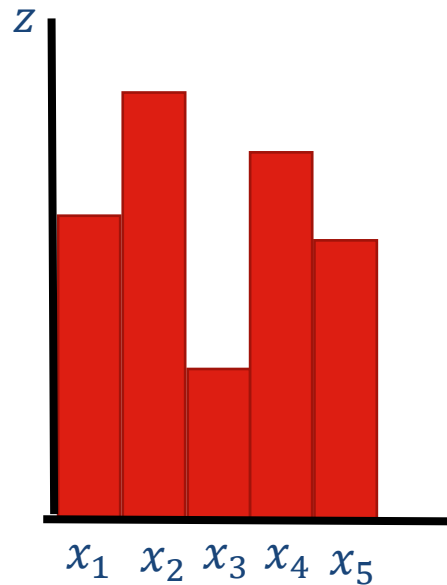


It is easy to minimize the largest value (minimax) or maximize the smallest value (maximin):

$$\min \left\{ \max_i x_i \right\}$$



$$\min z$$
$$z \geq x_i \quad \forall i$$

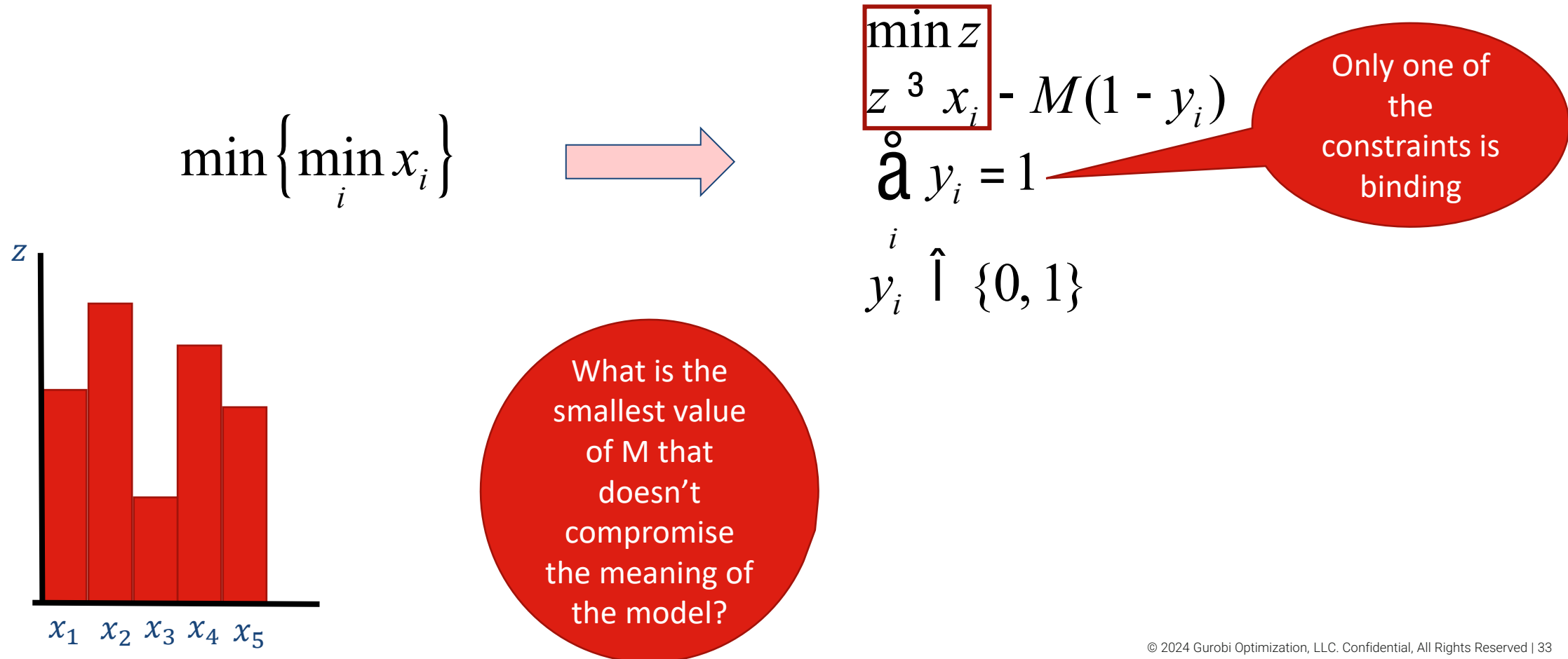


Example: minimizing completion time of last job in machine scheduling application

Min/max functions – Non-convex case

Harder to minimize the smallest value (minimin) or maximize the largest value (maximax)

- Use multiple indicator variables and a big-M value



Function type	Function	Python syntax
Minimization	$y = \min\{x_1, x_2, x_3\}$	<code>addGenConstrMin(y, [x1,x2,x3])</code>
Maximization	$y = \max\{x_1, x_2, x_3\}$	<code>addGenConstrMax(y, [x1,x2,x3])</code>
Absolute value	$y = x $	<code>addGenConstrAbs(y, x)</code>

Note:

General constraints are also available for C, C++, Java, .NET, and R; we use Python syntax simply for illustration.

And

$$x_1 = 1 \wedge x_2 = 1$$

$$x_1 + x_2 = 2$$

Or

$$x_1 = 1 \vee x_2 = 1$$

$$x_1 + x_2 \leq 1$$

Exclusive Or (not both)

$$x_1 = 1 \text{ xor } x_2 = 1$$

$$x_1 + x_2 = 1$$

At least/at most/counting

$$x_i = 1 \text{ for at least/most } 3 \text{ } i$$

$$\sum_i x_i \geq 3$$

If-then (implication)

$$\text{if } x_1 = 1 \text{ then } x_2 = 1$$

$$x_1 \leq x_2$$

And

$$y = (x_1 \wedge x_2)$$

$$y \leq x_1$$

$$y \leq x_2$$

$$y \leq x_1 + x_2 - 1$$

In other words,
 $y = x_1 * x_2$

Or

$$y = (x_1 \vee x_2)$$

$$y \leq x_1$$

$$y \leq x_2$$

$$y \leq x_1 + x_2$$

Exclusive Or (not both)

$$y = (x_1 \text{ xor } x_2)$$

$$\left. \begin{array}{l} y \leq x_1 - x_2 \\ y \leq x_2 - x_1 \end{array} \right\}$$

In other words,
 $y = |x_1 - x_2|$
y true when x1 or x2 true

$$y \leq x_1 + x_2$$

y false when x1 and x2 false

$$y \leq 2 - x_1 - x_2$$

y false when x1 and x2 true

Function type	Condition	Python syntax
And	$y = (x_1 = 1 \wedge x_2 = 1)$	<code>addGenConstrAnd(y, [x1,x2])</code>
Or	$y = (x_1 = 1 \vee x_2 = 1)$	<code>addGenConstrOr(y, [x1,x2])</code>

Note:

General constraints are also available for C, C++, Java, .NET, and R; we use Python syntax simply for illustration.

Logical conditions on constraints

- Add indicator variables for each constraint
- Enforce logical conditions via constraints on indicator variables
- And constraints
 - Just add the individual constraints to the model

$$\sum_i a_{1i}x_i \leq b_1$$

and

$$\sum_i a_{2i}x_i \leq b_2$$

- All other logical conditions require indicator variables

Use indicator for the satisfied constraint, plus big-M value:

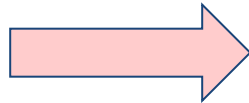
$$\sum_i a_{1i}x_i \leq b_1$$

or

$$\sum_i a_{2i}x_i \leq b_2$$

or

$$\sum_i a_{3i}x_i \leq b_3$$



$$\sum_i a_{1i}x_i \leq b_1 + M(1 - y_1)$$

$$\sum_i a_{2i}x_i \leq b_2 + M(1 - y_2)$$

$$\sum_i a_{3i}x_i \leq b_3 + M(1 - y_3)$$

$$y_1 + y_2 + y_3 \geq 1$$

$$y_1, y_2, y_3 \in \{0, 1\}$$

What is the smallest value of M that doesn't compromise the meaning of the model?

- Add a free variable to each equality constraint to measure slack or surplus
- Use indicator variable to designate whether slack/surplus is zero

$$\sum_i a_{ki} x_i = b_k$$



$$\sum_i a_{ki} x_i + w_k = b_k$$

$$w_k \leq M(1 - y_k)$$

$$w_k \geq -M(1 - y_k)$$

Slack

Surplus

$$y_1 + \dots + y_k \geq 1$$

$$y_1, \dots, y_k \in \{0,1\}$$

At least constraints

- Generalizes the "or" constraint
- Use indicator or big M (if not too big) for the satisfied constraints
- Count the binding constraints via a constraint on indicator variables

Example:

- At least 4 constraints must be satisfied with

$$y_1 + y_2 + \cdots + y_k \geq 4$$

$$\sum_i a_{ki} x_i + w_k = b_k$$

$$w_k \leq M(1 - y_k)$$

$$w_k \geq -M(1 - y_k)$$

$$y_1 + \cdots + y_k \geq 4$$

$$y_1, \dots, y_k \in \{0,1\}$$

Indicator General Constraint represents if-then logic

- If $z = 1$ then $x_1 + 2x_2 - x_3 \geq 2$

```
addGenConstrIndicator(z, 1, x1+2*x2-x3 >= 2)
```

- The condition ($z = 1$) must be a binary variable (z) and a value (0 or 1)

Many models have special kind of "or" constraint

$$x = 0 \vee 40 \leq x \leq 100$$

- This is a semi-continuous variable
- Semi-continuous variables are common in manufacturing, inventory, power generation, etc.
- Semi-integer variables are of similar form with an added integrality restriction

Two techniques for semi-continuous variables

1. Add the indicator yourself:

$$40y \leq x \leq 100y, y \in \{0,1\}$$

- Good performance but requires explicit upper bound on the semi-continuous variable

2. Let Gurobi handle variables you designate as semi-continuous (or semi-integer)

```
x = model.addVar(vtype=GRB.SEMICONT, lb=40, ub=100, name="x")  
x = model.addVar(vtype=GRB.SEMIINT, lb=40, ub=100, name="x")
```

- practical option when upper bound is large or non-existent

Combined logical constraints

Limit on number of non-zero semi-continuous variables

Easy if you use indicator variables

$$\begin{aligned} 40y_i &\leq x_i \leq 100y_i \\ \sum_i y_i &\leq 30 \end{aligned}$$

Need to model the logic yourself (instead of using semi-continuous variables), otherwise you cannot restrict the non-zero semi-variables.

Want big-M as tight (small) as possible

Example:

$$x_1 + x_2 \leq 10 + My$$

$$\text{if } x_1, x_2 \leq 100 \text{ then } M = 190$$

Presolve will do its best to tighten big-M values.

Tight, constraint-specific big-M values are better than a giant one-size-fits-all big-M

- Too large big-M leads to poor performance and numerical problems
- Pick big-M values specifically for each constraint
- Can look at statistics of presolved model to assess how well Gurobi reduced the big M coefficients

What is the smallest value of
M if $x_1, x_2 \leq 350$?

Want big-M as tight (small) as possible

Presolve will do its best to tighten big-M values.

But what if presolve doesn't provide any tighter big M values?

$$x_1 + x_2 \leq My$$

<other constraints involving x_1, x_2 >

$$x_1 + x_2 \geq 100000$$

Infeasible: $M < 100000$

Try again with rhs < 100000

Or run infeasibility finder; IIS may reveal group of constraints from which tighter M can be derived.

Feasible: Try again with rhs > 100000

Or solve a subproblem to determine M:

Maximize $x_1 + x_2$

s.t.

<all constraints in the model>

M = optimal subproblem objective value

New Optimization Based
Bound Tightening in Gurobi
10.0 does this on selected
individual variables

General constraint helper functions specific to gurobipy to simplify construction of constraints:

```
max_(), min_(), abs_(), and_(), or_(), norm()
```

```
model.addConstr(x == abs_(y))  
model.addConstr(x == or_(y,z,w))
```

Integrate general constraints with addConstrs():

```
X, Y, Gcons = model.addVars(10), model.addVars(10), {}  
for i in X:  
    Gcons[i] = model.addGenConstrMin(X[i], [Y[i], 10], name="Gc")
```

```
X, Y = model.addVars(10), model.addVars(10)  
Gcons = model.addConstrs((X[i] == min_(Y[i],10) for i in X), name="Gc")
```

General non-linear functions (of decision variables) are supported by **Gurobi 9.0+**

- e^x, a^x
 - $\ln(x), \log_a(x)$
 - $\sin(x), \cos(x), \tan(x)$
 - x^a
 - $ax^3 + bx^2 + cx + d$
- ```
addGenConstrExp(), addGenConstrExpA()
addGenConstrLog(), addGenConstrLogA()
addGenConstrSin(), addGenConstrCos(), addGenConstrTan()
addGenConstrPow()
addGenConstrPoly()
```
- Starting with **Gurobi 11.0**, these nonlinear functions are supported directly as well as via piecewise linear approximation.
    - Use the FuncNonlinear parameter and attribute to configure direct support

Non-convex quadratic functions are supported directly by **Gurobi 9.0+**

- Some special cases have been already supported prior to version 9.0 (e.g., products involving at least one binary decision variable)




# Elementary, univariate functions

- Gurobi 11.0 can handle selected univariate, smooth constraints  $f(x) = y$ 
  - Trigonometric, power functions, logarithms, exponentials, etc.
  - Use them as building blocks for more elaborate functions

Example: Suppose we want to model

$$f(\theta) = \sqrt{1 + \theta^2} + \ln(\theta + \sqrt{1 + \theta^2}) \leq 2, \quad \theta \geq 0$$



Then we introduce auxiliary variables  $u, v, w, z \geq 0$  and constraints as follows:

$$u = 1 + \theta^2, \quad u = v^2, \quad w = \theta + v, \quad z = \ln w$$

Then  $f(\theta) \leq 2$  can be represented as  $v + z \leq 2$

# Multiple Objectives

---

## Real-world optimization problems often have multiple, competing objectives:

- Cost functions/Revenue
- Satisfaction/Target achievement
- Fairness
- KPIs
- Error/Feasibility
- Switching Configurations

## Approaches to handling more than one objective function:

- Integration into a single objective function by using a weighted combination of multiple objectives
- Hierarchical approach: solve model for each objective but limit degradation of previous results
- ... or a combination of both



## Easy definition of multiple objectives

```
model.setObjectiveN(LinExpr, index, ...)
```

### Variant 1

```
coef1 = [0, 1, 2, 3, 4]
coef2 = [4, 3, 2, 1, 0]
x = model.addVars(5)
```

```
model.setObjectiveN(x.prod(coef1), 0, priority=2, weight=1)
model.setObjectiveN(x.prod(coef2), 1, priority=1, weight=1)
```

Used with  
getMultiobjEnv() to  
set different  
parameters for  
different  
subproblems

### Variant 2

```
model.setObjectiveN(x[1]+2*x[2]+3*x[3]+4*x[4], 0, priority=2, weight=1)
model.setObjectiveN(4*x[0]+3*x[1]+2*x[2]+x[3], 1, priority=1, weight=1)
```

## Enhanced termination control for multi-objective optimization

```
model.getMultiobjEnv()
```

```
env0 = model.getMultiobjEnv(0)
env1 = model.getMultiobjEnv(1)

env0.setParam('TimeLimit',100)
env1.setParam('TimeLimit',10)

model.optimize()
model.discardMultiobjEnvs()
```

- Allows for fine-grained control of each multi-objective optimization pass
  - Algorithmic choices
  - Termination criteria
- One optimization pass per objective priority level
  - Settings for additional objectives of same priority level are ignored

**Note: MIP starts are only used for first priority level objective solve.**

# Example of multiple objectives

## Workforce Scheduling Demo:

- First, minimize cost
- Then make the model “fair”

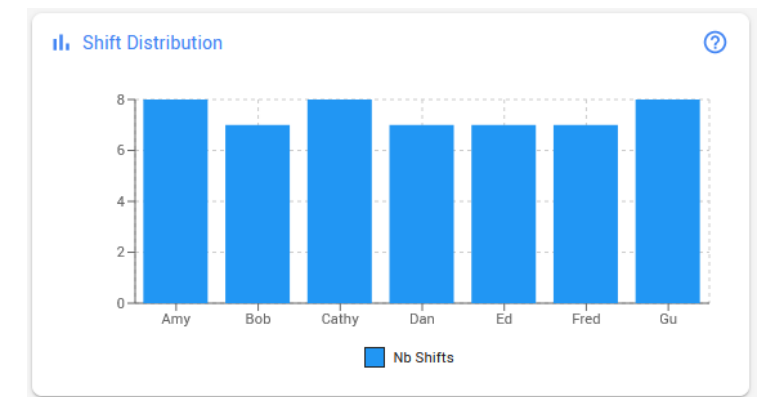
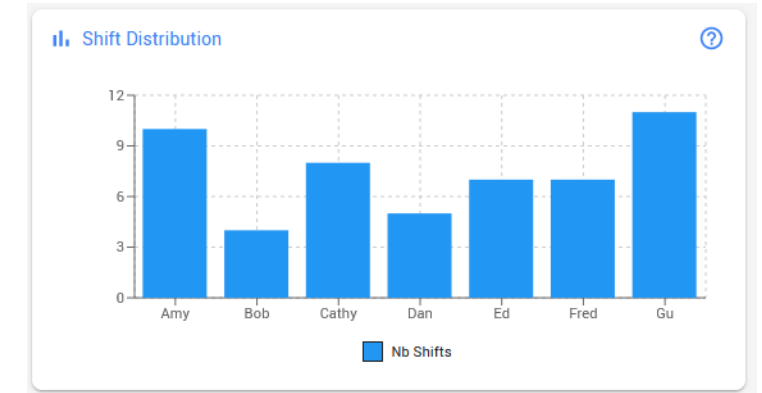
```
model.setObjectiveN(totSlack, index=index, priority=2,
 reltol=extra_worker_trade_off, name='TotalSlack')
model.setObjectiveN(max_shift - min_shift, index=index,
 priority=1, name='Fairness')
```

## Tolerances

Allow deviation from optimality

Gives “room” for finding lower-priority objectives

Could specify absolute instead of relative tolerance





# Summary and Additional Learning

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- Free variables can be expressed as difference of two nonnegative variables
- Big-Ms can pose challenges despite Gurobi's powerful bound strengthening
  - SOSs can help
  - IISs of reversed bounds can help
  - Optimization Based Bound Tightening can help
    - Gurobi parameter (OBBT) for individual variables
    - Create your own subproblem for more complex expressions
- Convex models usually are much easier to solve than nonconvex ones
- Gurobi continues to add support for more general constraints, facilitating the model development process
  - Before doing it yourself, check if there's an API for that
- Gurobipy modeling extensions (e.g. tupledict) enable simpler and faster code for extraction of subsets, an essential part of model building





# Check out our Modeling Examples in Jupyter Notebook:

[www.gurobi.com/resource/modeling-examples-using-the-gurobi-python-api-in-jupyter-notebook/](http://www.gurobi.com/resource/modeling-examples-using-the-gurobi-python-api-in-jupyter-notebook/)



## Tutorial Example

### Introductory

This modeling tutorial is at the introductory level, where we assume that you know Python and basic optimization methods.

| Example                                                     | Description                                                                                                                                |
|-------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------|
| <a href="#">Intro to Mathematical Optimization Modeling</a> | Learn the key components in the formulation of an optimization problem and how to use the Gurobi Optimizer to compute an optimal solution. |

### Intermediate

These modeling examples are at the intermediate level, where we assume that you have some experience with Python and should know Python and be familiar with the Gurobi Python API.

| Example                                                | Description                                                                                                                                                                                     |
|--------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <a href="#">Agricultural Pricing*</a>                  | Determine the prices and demand for the products of a country in order to maximize total revenue from the sales of those products.                                                              |
| <a href="#">Best Feature Selection for Forecasting</a> | A linear regression problem that minimizes the sum of squares subject to the constraint that the number of non-zero feature weights should be less than or equal to a given upper limit.        |
| <a href="#">Customer Assignment</a>                    | Address the optimal placement of facilities (e.g., candidate locations) in order to minimize the total distance between a company's facilities and its customers.                               |
| <a href="#">Electrical Power Generation*</a>           | An electrical power generation problem (unit commitment problem) by selecting the optimal set of power stations to turn on in order to meet the anticipated power demand over a 24-hour period. |
| <a href="#">Factory Planning*</a>                      | Solve a production planning problem at the factory level.                                                                                                                                       |

## Modeling Examples

\*Problems from the fifth edition of Model Building in Mathematical Programming, by V. Chvátal.

### Beginner

These modeling examples are at the beginner level, where we assume you know Python and basic optimization methods.

| Example                                                        | Description                                                                                                                                                 |
|----------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <a href="#">Creating the Optimal Fantasy Basketball Lineup</a> | Utilizes supervised machine learning to predict fantasy scores from historical data and formulates an integer programming model to find the optimal lineup. |
| <a href="#">3D Tic-Tac-Toe*</a>                                | Arrange X's and O's on a three-dimensional board to minimize the number of empty cells.                                                                     |
| <a href="#">Cell Tower Coverage</a>                            | A simple covering problem that builds a set of towers to provide signal coverage to the maximum number of people possible.                                  |

### Advanced

These modeling examples are at the advanced level, where we assume that you know Python and have experience building mathematical optimization models. Typically, the objective function and/or constraints are non-linear or the problem is solved using the Gurobi Python API.

| Example                                    | Description                                                                                                                                           |
|--------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------|
| <a href="#">Decentralization Planning*</a> | For a given a set of departments of a company, determine the "best" location of each department in order to maximize gross margins.                   |
| <a href="#">Farm Planning*</a>             | A production planning problem, where decisions must be made regarding which products to produce and which resources to use to produce those products. |

# Model Building in Mathematical Programming, by H.P. Williams



# Thank You

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